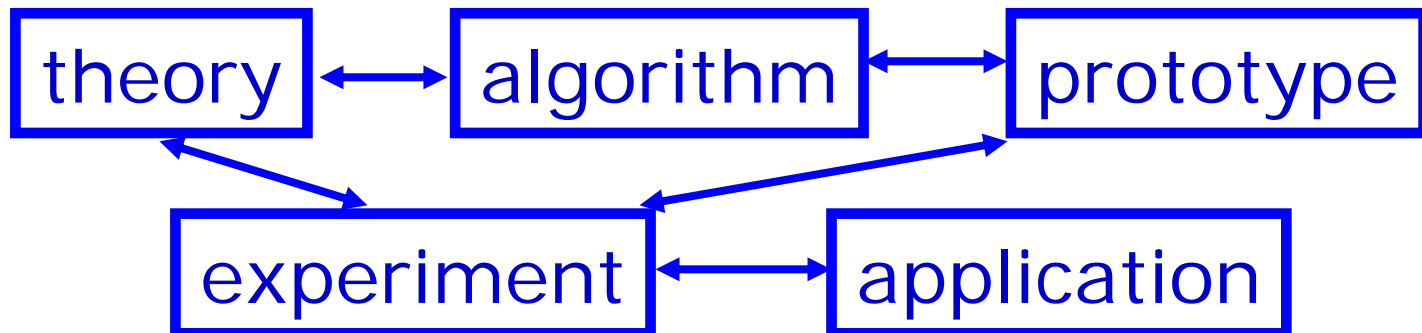


# Flow Control Theory for Practitioners

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Steven Low  
EAS, Caltech



# Acknowledgments

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## □ Caltech

- L. Andrews, J. Doyle, S. Hegde, C. Jin, G. Lee, L. Li, H. Newman, A. Tang, J. Wang, D. Wei, B. Wydrowski

## □ UCLA

- F. Paganini

## □ Princeton

- M. Chiang, L. Peterson, L. Wang

## □ KTH

- K. Jacobsson



# Role of (current) theory

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- It is **not** (yet) for
  - Automatic synthesis of new congestion control algorithms
  - Replacing intuitions, experiments, heuristics
  
- But for providing structure and clarity
  - To refine intuition
  - To guide design
  - To suggest ideas
  - To explore boundaries
  - To assess global structural properties, e.g. scalability
  
- Risk
  - “All models are wrong”
  - “... some are useful”

# Outline

---

## Samples of interactions between theory & experiments

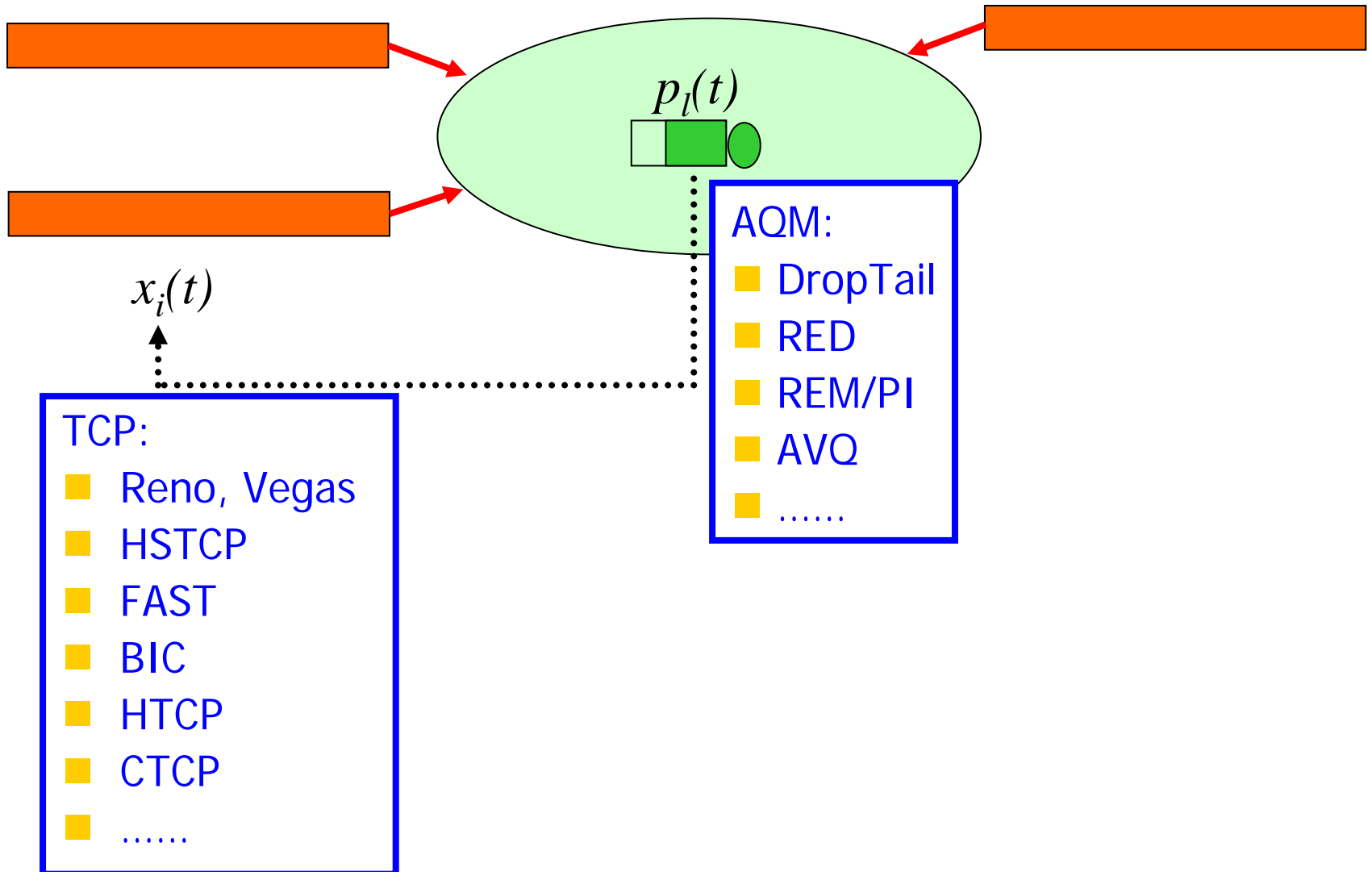
- Duality model of TCP
  - Theory: equilibrium point characterized by an optimization problem
  - Experimental validation: Vegas
- An accurate link model
  - Theory: a new joint link model
  - Application: FAST stability
- Heterogeneous protocols
  - Motivation: FAST+Reno
  - Theory: multiple equilibria, global uniqueness

# Congestion control

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- ❑ Challenge: available info must be end-to-end
- ❑ Implicit congestion feedback
  - Loss probability: likelihood of a packet being delivered correctly
  - Round-trip time: time it takes for a packet to reach its destination and for its ack to return to the sender
- ❑ Explicit congestion feedback: marks, rates

# TCP & AQM



## Historically

- ❑ Packet level implemented first
- ❑ Flow level understood as after-thought
- ❑ But flow level design determines
  - performance, fairness, stability

## Now: can forward engineer

- ❑ Sophisticated theory on equilibrium & stability (optimization+control)
- ❑ Given (application) utility functions, can design provably scalable TCP algorithms

# Packet level

## □ Reno

AIMD(1, 0.5)

$$\text{ACK: } W \leftarrow W + 1/W$$

$$\text{Loss: } W \leftarrow W - 0.5W$$

## □ HSTCP

AIMD(a(w), b(w))

$$\text{ACK: } W \leftarrow W + a(w)/W$$

$$\text{Loss: } W \leftarrow W - b(w)W$$

## □ STCP

MIMD(a, b)

$$\text{ACK: } W \leftarrow W + 0.01$$

$$\text{Loss: } W \leftarrow W - 0.125W$$

## □ FAST

$$\text{RTT: } W \leftarrow W \cdot \frac{\text{baseRTT}}{\text{RTT}} + \alpha$$



# Flow level: Reno, HSTCP, STCP, FAST

- **Common** flow level dynamics!

$$\dot{w}_i(t) = \kappa(t) \cdot \left( 1 - \frac{p_i(t)}{U_i'(t)} \right)$$

window adjustment	=	control gain	flow level goal
----------------------	---	-----------------	--------------------

- **Different** gain  $\kappa$  and utility  $U_i$ 
  - They determine equilibrium and stability
- **Different** congestion measure  $p_i$ 
  - Loss probability (Reno, HSTCP, STCP)
  - Queueing delay (Vegas, FAST)

# Flow level: Reno, HSTCP, STCP, FAST

## □ **Similar** flow level equilibrium

$$\text{Reno} \quad x_i = \frac{1}{T_i} \cdot \frac{\alpha}{p_i^{0.5}} \quad \text{pkts/sec}$$

$$\text{HSTCP} \quad x_i = \frac{1}{T_i} \cdot \frac{\alpha}{p_i^{0.84}}$$

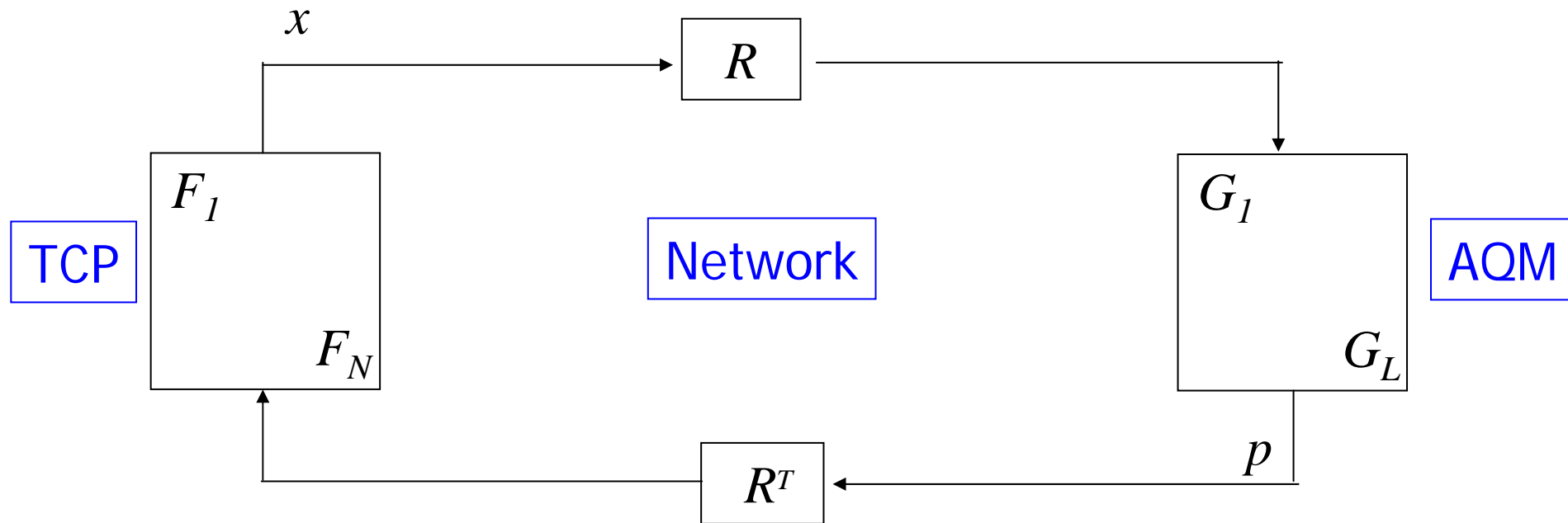
$$\text{STCP} \quad x_i = \frac{1}{T_i} \cdot \frac{\alpha}{p_i}$$

$$\text{FAST} \quad x_i = \frac{\alpha}{p_i}$$

$\alpha = 1.225$  (Reno),  $0.120$  (HSTCP),  $0.075$  (STCP)

# Network model

---



$R_{li} = 1$  if source  $i$  uses link  $l$

$$x(t+1) = F(R^T p(t), x(t))$$

$$p(t+1) = G(p(t), Rx(t))$$

IP routing

Reno, Vegas

DT, RED, ...

# Network model: example

---

Reno:  
Jacobson  
1989

for every RTT (AI)  
{ W += 1 }  
for every loss (MD)  
{ W := W/2 }

$$x_i(t+1) = \frac{1}{T_i^2} - \frac{x_i^2}{2} \sum_l R_{li} p_l(t) \quad \leftarrow \begin{array}{l} \text{AI} \\ \text{MD} \end{array}$$
$$p_l(t+1) = G_l \left( \sum_i R_{li} x_i(t), p_l(t) \right) \quad \leftarrow \text{TailDrop}$$

# Network model: example

---

FAST:

Jin, Wei, Low  
2004

Wei, Jin, Low,  
Hegde 2007

periodically

$$\left\{ \begin{array}{l} W := \frac{\text{baseRTT}}{\text{RTT}} W + \alpha \end{array} \right.$$

$$x_i(t+1) = x_i(t) + \frac{\gamma_i}{T_i} \left( \alpha_i - x_i(t) \sum_l R_{li} p_l(t) \right)$$

$$p_l(t+1) = p_l(t) + \frac{1}{c_l} \left( \sum_i R_{li} x_i(t) - c_l \right)$$

# Reverse engineering

Protocol (Reno, Vegas, RED, REM/PI...)

$$\begin{aligned}x(t+1) &= F(p(t), x(t)) \\ p(t+1) &= G(p(t), x(t))\end{aligned}$$

## Equilibrium

- Performance
  - Throughput, loss, delay
- Fairness
- Utility

## Dynamics

- Local stability
- Global stability

# Duality model of TCP/AQM

---

□ TCP/AQM  $x^* = F(R^T p^*, x^*)$

$$p^* = G(p^*, Rx^*)$$

□ Equilibrium  $(x^*, p^*)$  primal-dual optimal:

$$\max_{x \geq 0} \sum U_i(x_i) \quad \text{subject to} \quad Rx \leq c$$

■  $F$  determines utility function  $U$

■  $G$  guarantees complementary slackness

■  $p^*$  are Lagrange multipliers

Kelly, Maloo, Tan 1998  
Low, Lapsley 1999

## Uniqueness of equilibrium

■  $x^*$  is unique when  $U$  is strictly concave

■  $p^*$  is unique when  $R$  has full row rank

# Duality model of TCP/AQM

---

□ TCP/AQM  $x^* = F(R^T p^*, x^*)$

$$p^* = G(p^*, Rx^*)$$

□ Equilibrium  $(x^*, p^*)$  primal-dual optimal:

$$\max_{x \geq 0} \sum U_i(x_i) \quad \text{subject to} \quad Rx \leq c$$

■  $F$  determines utility function  $U$

■  $G$  guarantees complementary slackness

■  $p^*$  are Lagrange multipliers

Kelly, Maloo, Tan 1998  
Low, Lapsley 1999

The underlying concave program also  
leads to simple dynamic behavior



# Reverse engineering TCP

---

□ Equilibrium  $(x^*, p^*)$  primal-dual optimal:

$$\max_{x \geq 0} \sum U_i(x_i) \quad \text{subject to } Rx \leq c$$

Mo & Walrand 2000:

$$U_i(x_i) = \begin{cases} \log x_i & \text{if } \alpha = 1 \\ (1 - \alpha)^{-1} x_i^{1 - \alpha} & \text{if } \alpha \neq 1 \end{cases}$$

- $\alpha = 1$  : Vegas, FAST, STCP
- $\alpha = 1.2$ : HSTCP
- $\alpha = 2$  : Reno
- $\alpha = \infty$  : XCP (single link only)

# Reverse engineering TCP

---

□ Equilibrium  $(x^*, p^*)$  primal-dual optimal:

$$\max_{x \geq 0} \sum U_i(x_i) \quad \text{subject to } Rx \leq c$$

Mo & Walrand 2000:

$$U_i(x_i) = \begin{cases} \log x_i & \text{if } \alpha = 1 \\ (1 - \alpha)^{-1} x_i^{1 - \alpha} & \text{if } \alpha \neq 1 \end{cases}$$

- $\alpha = 0$ : maximum throughput
- $\alpha = 1$ : proportional fairness
- $\alpha = 2$ : min delay fairness
- $\alpha = \infty$ : maxmin fairness

# Some implications

---

- Equilibrium
  - Always exists, unique if  $R$  is full rank
  - Bandwidth allocation independent of AQM or arrival
  - Can predict macroscopic behavior of large scale networks
  
- Counter-intuitive throughput behavior
  - Fair allocation is not always inefficient
  - Increasing link capacities do not always raise aggregate throughput
  
- FAST TCP
  - Design, analysis, experiments

[Tang, Wang, Low, ToN 2006]

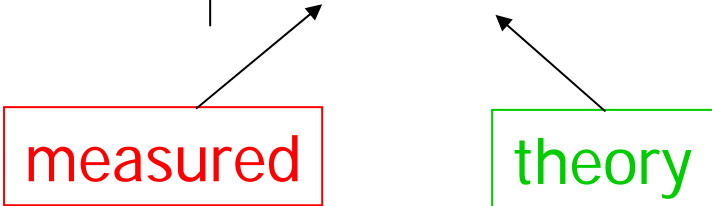
[Wei, Jin, Low, Hegde ToN 2006]

# Validation

---

	Source 1	Source 3	Source 5
RTT (ms)	17.1 (17)	21.9 (22)	41.9 (42)
Rate (pkts/s)	1205 (1200)	1228 (1200)	1161 (1200)
Window (pkts)	20.5 (20.4)	27 (26.4)	49.8 (50.4)
Avg backlog (pkts)	9.8 (10)		

measured theory



- Single link, capacity = 6 pkts/ms
- 5 sources with different propagation delays,  $\alpha_s = 2$  pkts/RTT

# Persistent congestion

---

- Vegas exploits buffer process to compute prices (queueing delays)
- Persistent congestion due to
  - Coupling of buffer & price
  - Error in propagation delay estimation
- Consequences
  - Excessive backlog
  - Unfairness to older sources

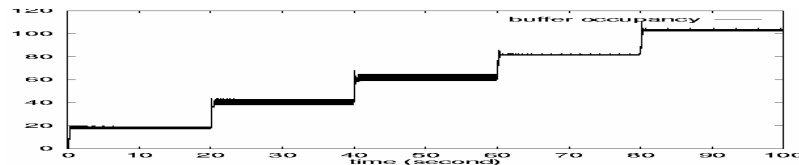
## Theorem

*A relative error of  $\varepsilon_s$  in propagation delay estimation distorts the utility function to*

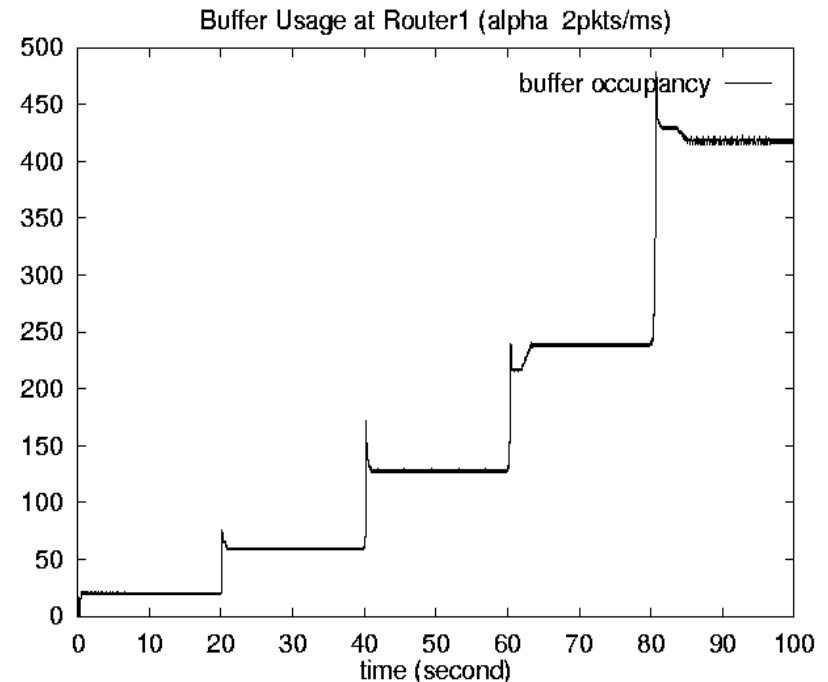
$$\hat{U}_s(x_s) = (1 + \varepsilon_s) \alpha_s d_s \log x_s + \varepsilon_s d_s x_s$$

# Evidence

---



Without estimation error



With estimation error

- Single link, capacity = 6 pkt/ms,  $\alpha_s = 2$  pkts/ms,  $d_s = 10$  ms
- With finite buffer: Vegas reverts to Reno

# Evidence

---

Source rates (pkts/ms)

#	src1	src2	src3	src4	src5
1	5.98 (6)				
2	2.05 (2)	3.92 (4)			
3	0.96 (0.94)	1.46 (1.49)	3.54 (3.57)		
4	0.51 (0.50)	0.72 (0.73)	1.34 (1.35)	3.38 (3.39)	
5	0.29 (0.29)	0.40 (0.40)	0.68 (0.67)	1.30 (1.30)	3.28 (3.34)

#	queue (pkts)	baseRTT (ms)
1	19.8 (20)	10.18 (10.18)
2	59.0 (60)	13.36 (13.51)
3	127.3 (127)	20.17 (20.28)
4	237.5 (238)	31.50 (31.50)
5	416.3 (416)	49.86 (49.80)

[Low, Peterson, Wang, JACM 2002]

# Outline

---

## □ Duality model of TCP

- Theory: equilibrium point characterized by an optimization problem
- Experimental validation: Vegas

## □ An accurate link model

- Theory: a new joint link model
- Application: FAST stability

[Tang, Jacobsson, Andrew, Low, Infocom 07]

## □ Heterogeneous protocols

- Motivation: FAST+Reno
- Theory: multiple equilibria, global uniqueness





# FAST TCP

FAST:

Jin, Wei, Low  
2004

periodically

{

$$W := \gamma \left( \frac{\text{baseRTT}}{\text{RTT}} W + \alpha \right) + (1 - \gamma) W$$

}

$$\dot{w}_i = -\gamma \frac{q_i(t)}{(d_i + q_i(t))^2} w_i(t) + \gamma \frac{\alpha_i}{d_i + q_i(t)}$$

$$q_i(t) = p(t - \tau_i^b)$$



Single Link



# Link model 1: integrator model

aggregate FAST rate

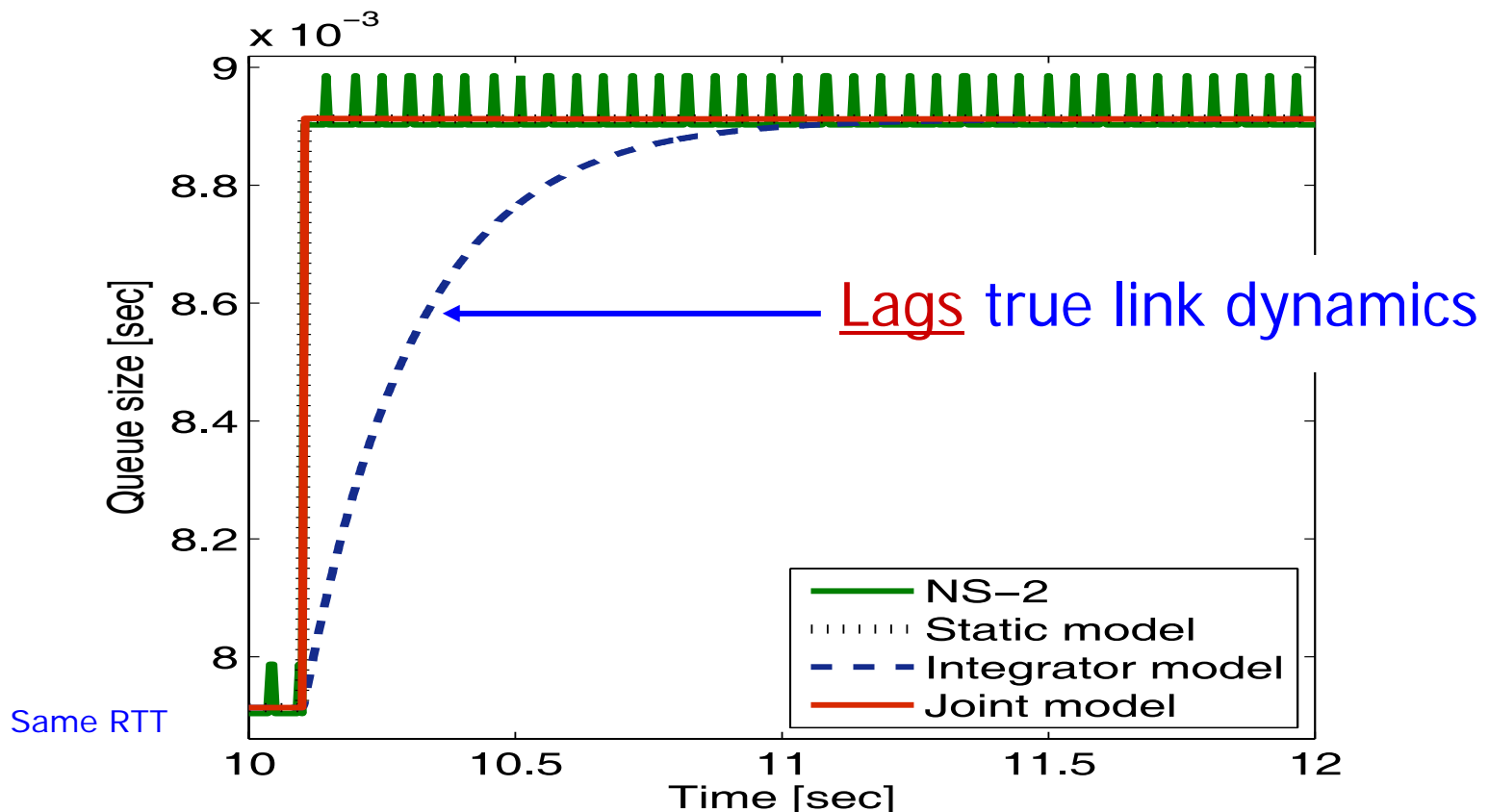
$$\dot{p} = \frac{1}{c} \left( \sum_i \frac{w_i(t - \tau_i^f)}{d_i + p(t)} + x_0(t) - c \right)$$

cross traffic rate



# Link model 1: integrator model

$$\dot{p} = \frac{1}{c} \left( \sum_i \frac{w_i (t - \tau_i^f)}{d_i + p(t)} + x_0(t) - c \right)$$





# Link model 2: static model

D. Wei, 2003:

$$\sum_i \frac{w_i(t - \tau_i^f)}{d_i + p(t)} + x_0(t) = c$$

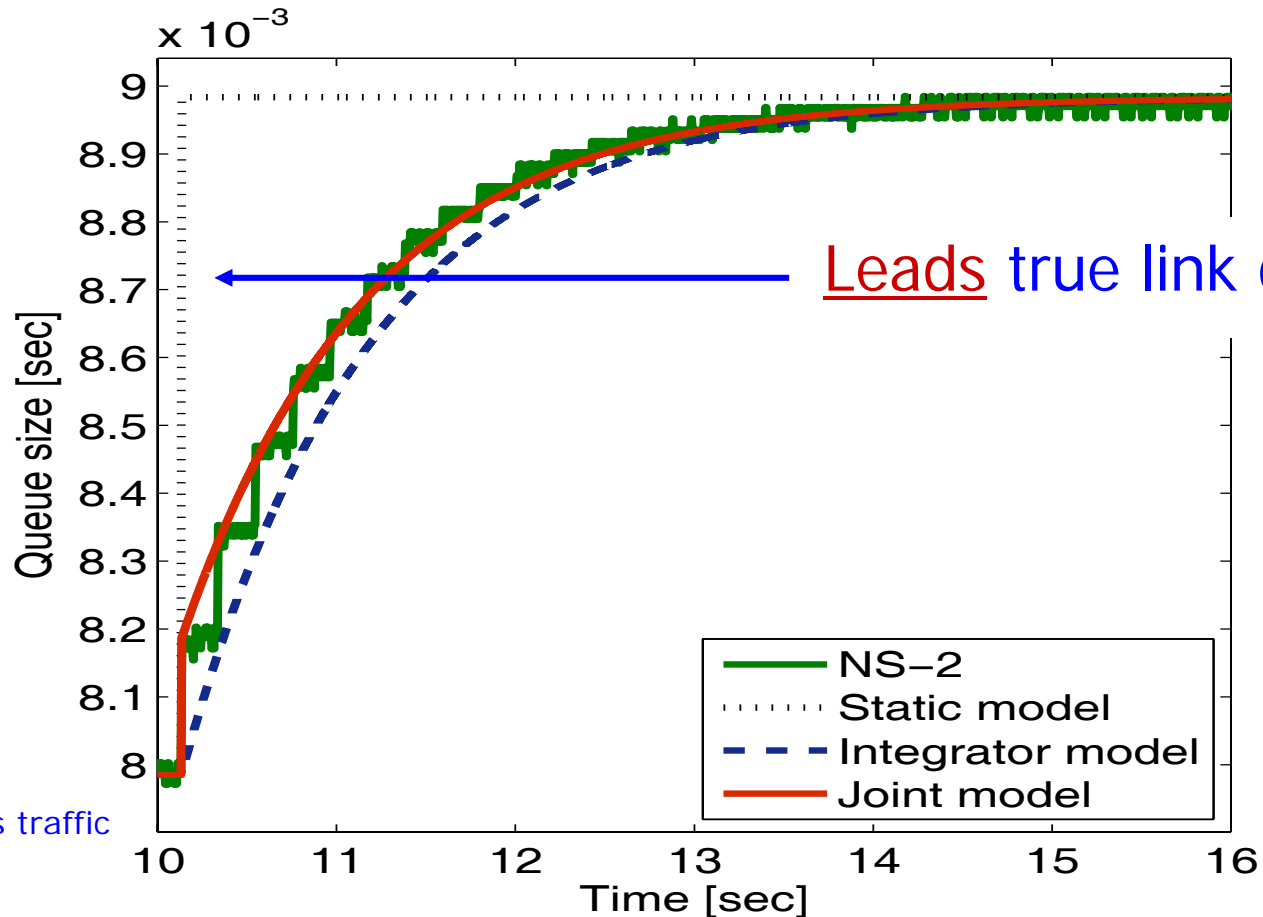
## Motivations

- Ack-clocking: input rate = capacity after 1 RTT
- Fast link dynamics



# Link model 2: static model

$$\sum_i \frac{w_i (t - \tau_i^f)}{d_i + p(t)} + x_0(t) = c$$





# Link model 3: joint model

K. Jacobsson  
etc, 2006:

$$\dot{p} = \frac{1}{c} \left[ \left( \sum_i \frac{w_i(t - \tau_i^f)}{d_i + p(t)} + \dot{w}_i(t - \tau_i^f) \right) + x_0(t) - c \right]$$

$\dot{w}_i(t - \tau_i^f) = 0$  : Reduces to integrator model

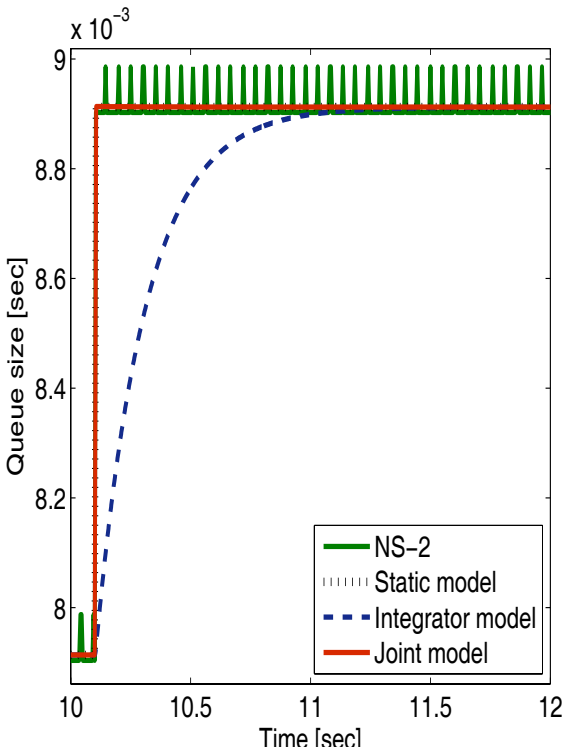
and  $\dot{p} = 0$  : Reduces to static model



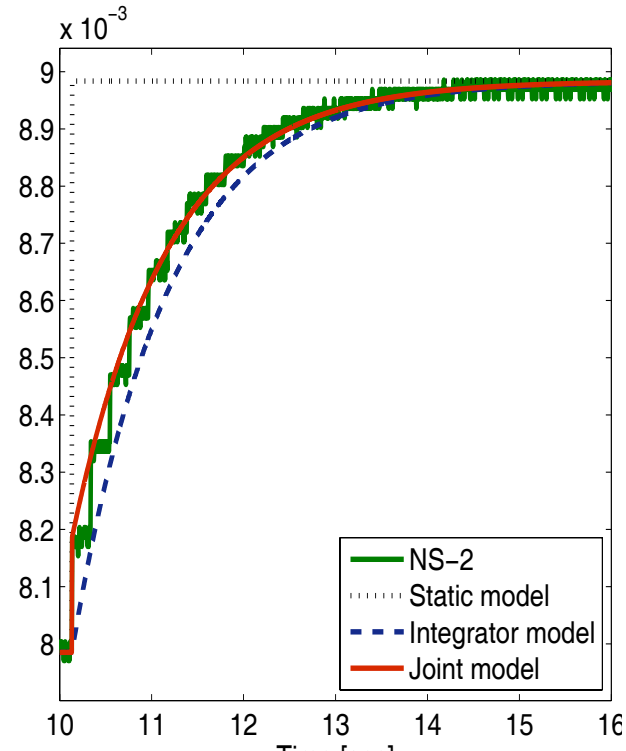
# Link model 3: joint model

$$\dot{p} = \frac{1}{c} \left[ \left( \sum_i \frac{w_i(t - \tau_i^f)}{d_i + p(t)} + \dot{w}_i(t - \tau_i^f) \right) + x_0(t) - c \right]$$

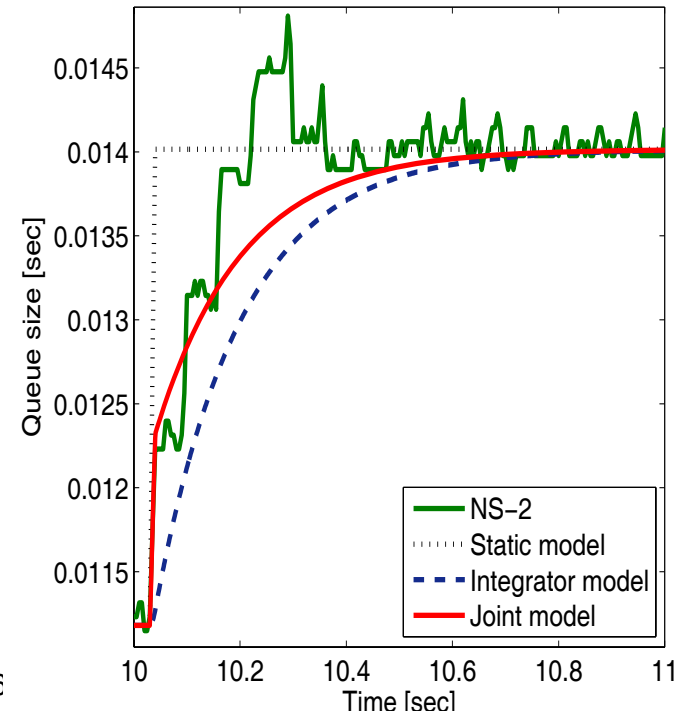
Same RTT, no cross traffic



Same RTT, cross traffic



Different RTTs, no cross traffic





# FAST TCP

Source model:

$$\dot{w}_i = -\gamma \frac{q_i(t)}{(d_i + q_i(t))^2} w_i(t) + \gamma \frac{\alpha_i}{d_i + q_i(t)}$$

$$q_i(t) = p(t - \tau_i^b) \quad \leftarrow \text{Single Link}$$

Link (joint) model:

$$\dot{p} = \frac{1}{c} \left[ \left( \sum_i \frac{w_i(t - \tau_i^f)}{d_i + p(t)} + \dot{w}_i(t - \tau_i^f) \right) + x_0(t) - c \right]$$





# FAST TCP: linear stability

## Theorem

FAST TCP is linearly stable for arbitrary delay provided

$$\gamma < 0.94$$

Resolves a major discrepancy between previous predictions and empirical experience

 FAST TCP: linearized model

Loop gain:

$$L(s) = \sum_i \mu_i L_i(s)$$

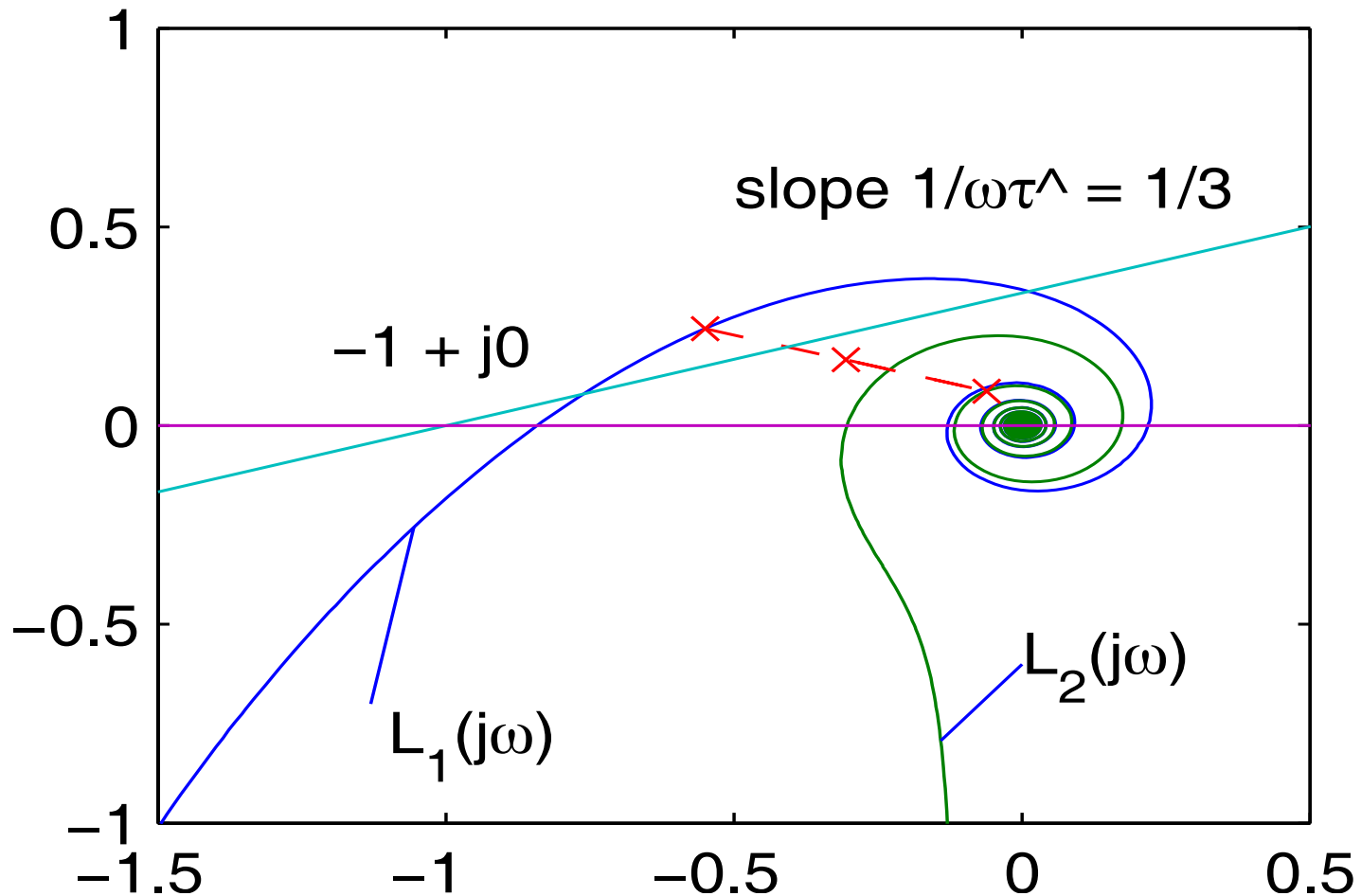
$$L_i(s) = \frac{s + \frac{1}{\tau_i}}{s + \frac{1}{\hat{\tau}}} \cdot \frac{\gamma d_i e^{-\tau_i s}}{\tau_i^2 s + \gamma q}$$

$$\mu_i = \frac{\alpha_i}{c \sum_n \alpha_n} \qquad \frac{1}{\hat{\tau}} = \sum_i \mu_i \frac{1}{\tau_i}$$



# Nyquist stability analysis

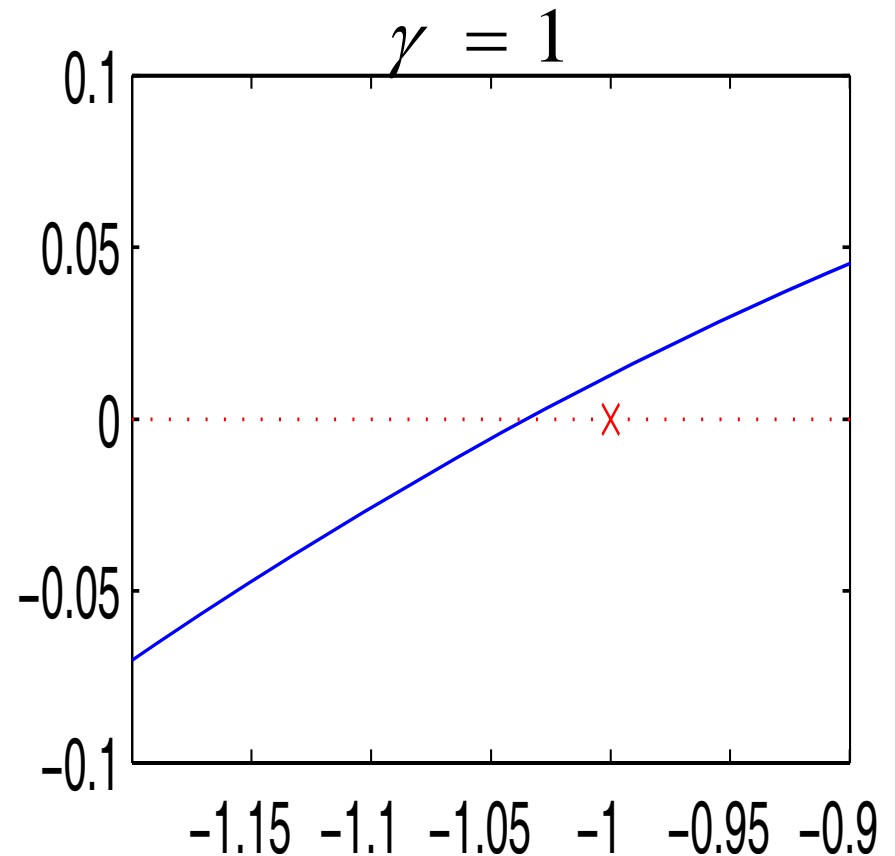
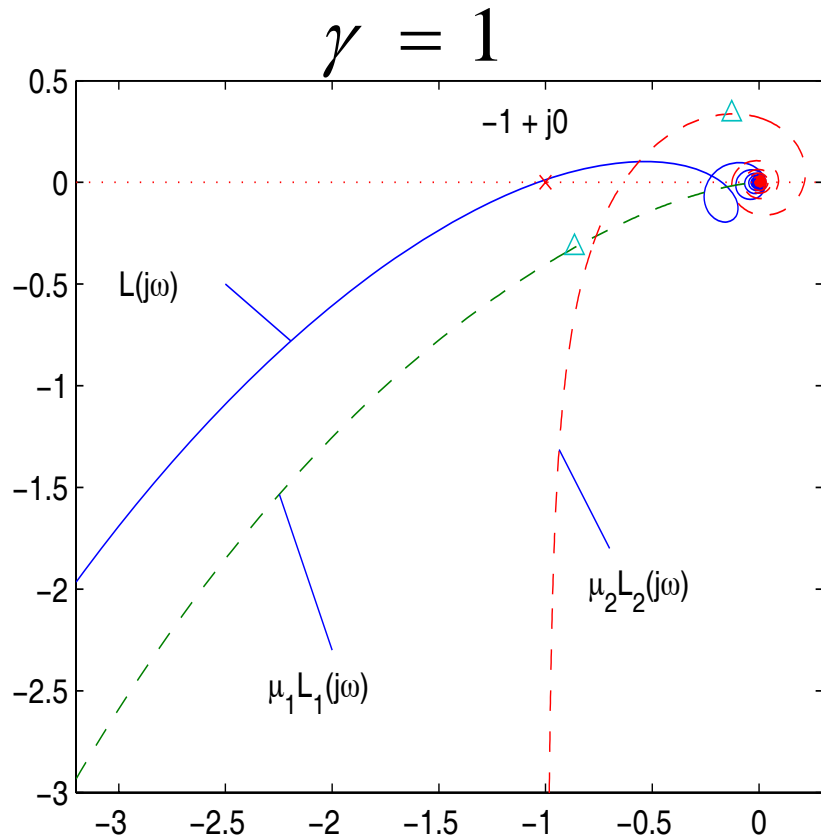
$$L(j\omega) = \sum_i \mu_i L_i(j\omega)$$





# Stability condition can be “tight”

Linearly stable if  $\gamma < 0.94$





# Comparison of 3 link models

- ❑ Single link with capacity 10,000 pkts/s
- ❑ Propagation delays: 400ms, 700ms
- ❑  $\alpha = 50$  pkts

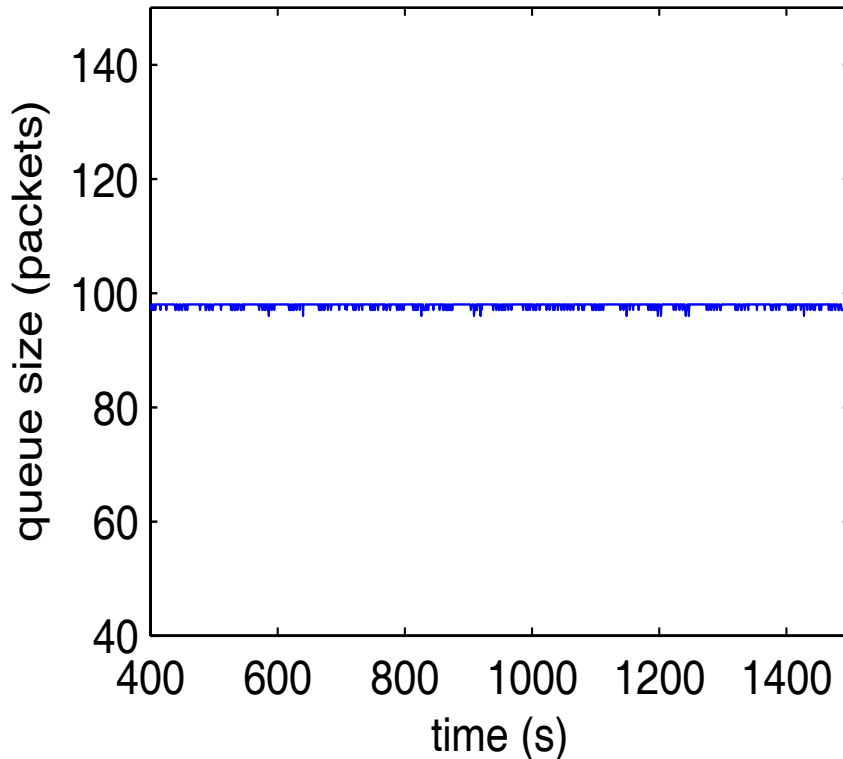
## Critical step size

- ❑ Integrator model: 1.23
- ❑ Static model: 1.80
- ❑ Joint model: 1.69



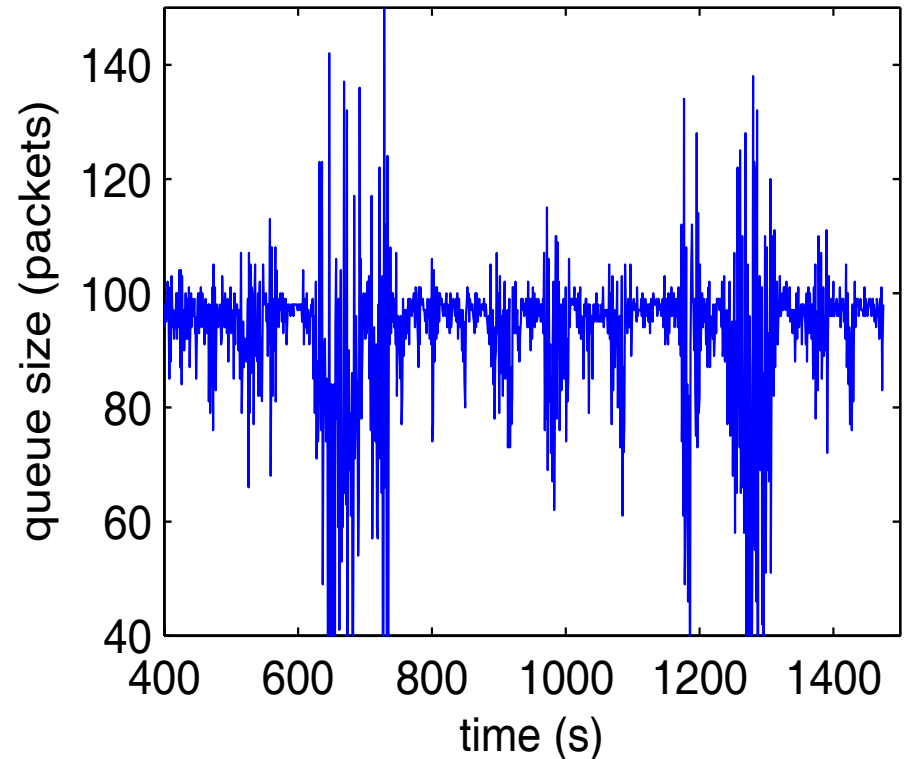
# Comparison of 3 link models

$$\gamma = 1.23$$



Integrator model too conservative

$$\gamma = 1.80$$

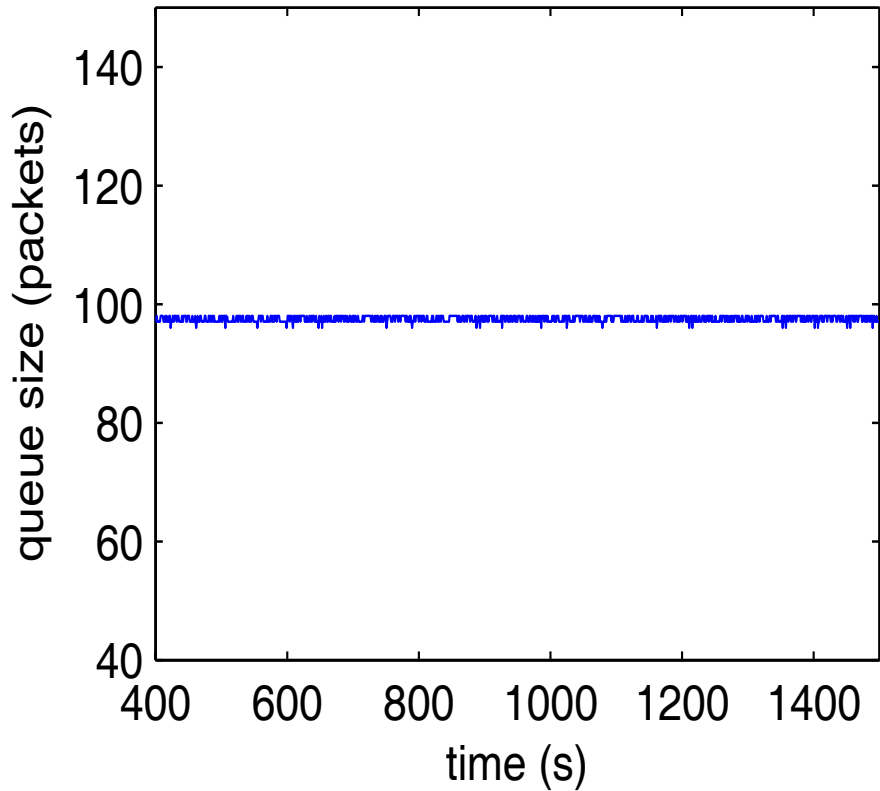


Static model too aggressive

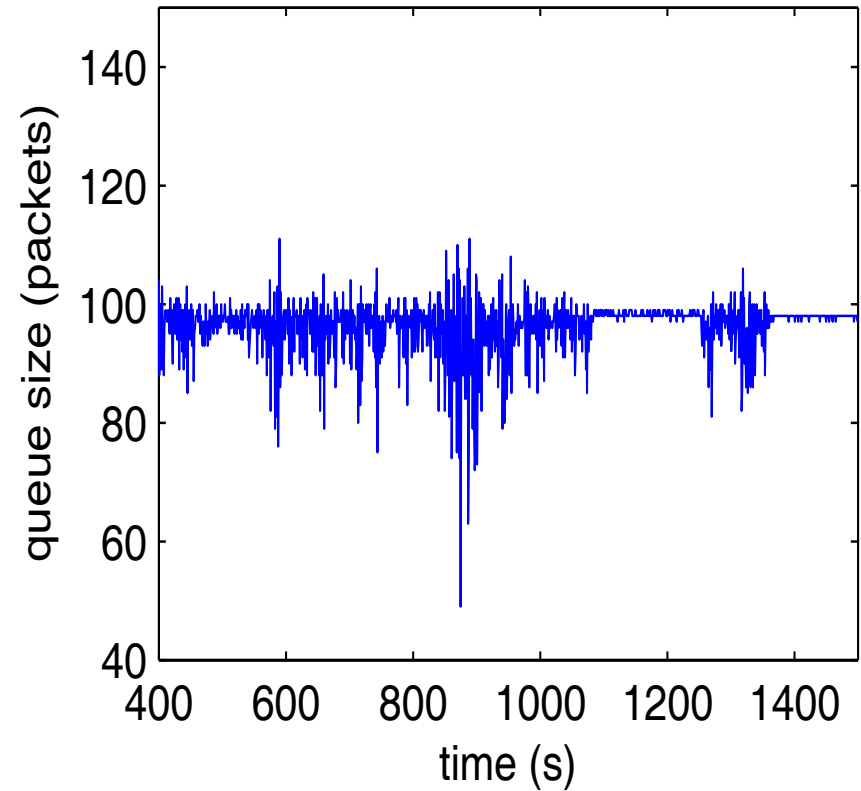


# Comparison of 3 link models

$$\gamma = 1.65$$

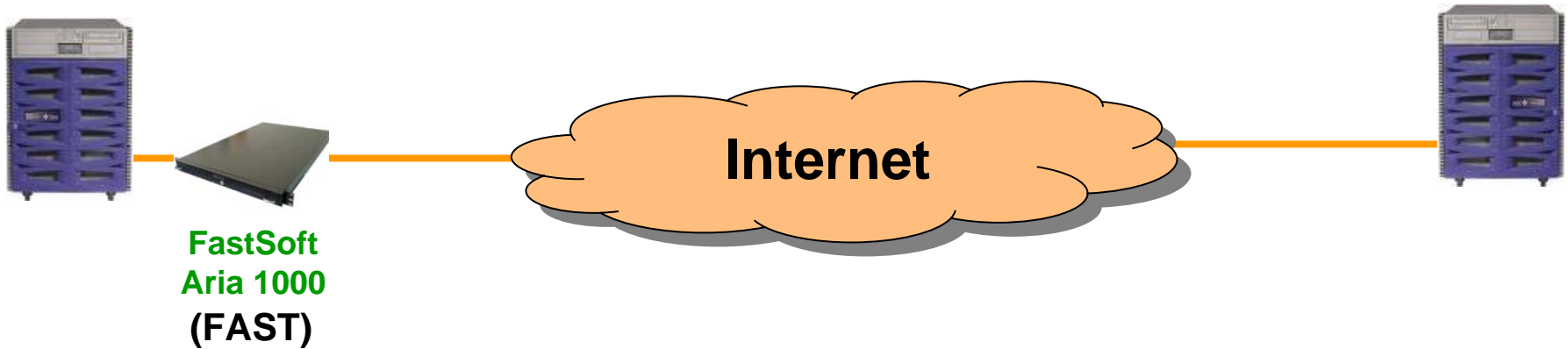


$$\gamma = 1.75$$

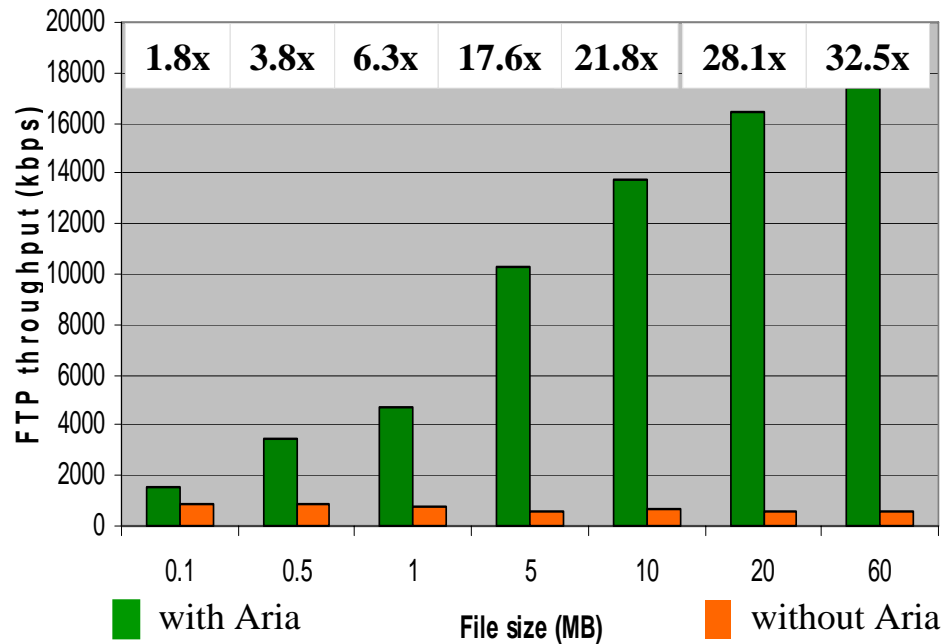


Joint model prediction:  $\gamma < 1.69$

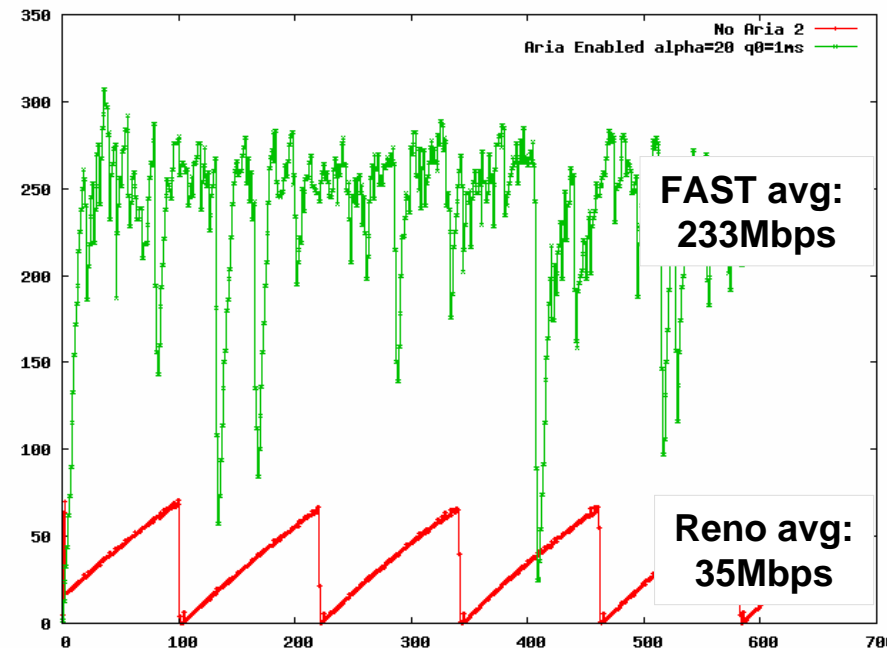
# Commercial Deployment: FAST in a box



## Throuput: LA → Tokyo



## Throuput: San Fran → MIT







# Outline

- Duality model of TCP
  - Theory: equilibrium point characterized by an optimization problem
  - Experimental validation: Vegas
- An accurate link model
  - Theory: a new joint link model
  - Application: FAST stability
- Heterogeneous protocols
  - Motivation: FAST+Reno
  - Theory: multiple equilibria, global uniqueness

[Tang, Wang, Low, Chiang, ToN 2007]

[Tang, Wang, Hegde, Low, Comp Networks, 2005]

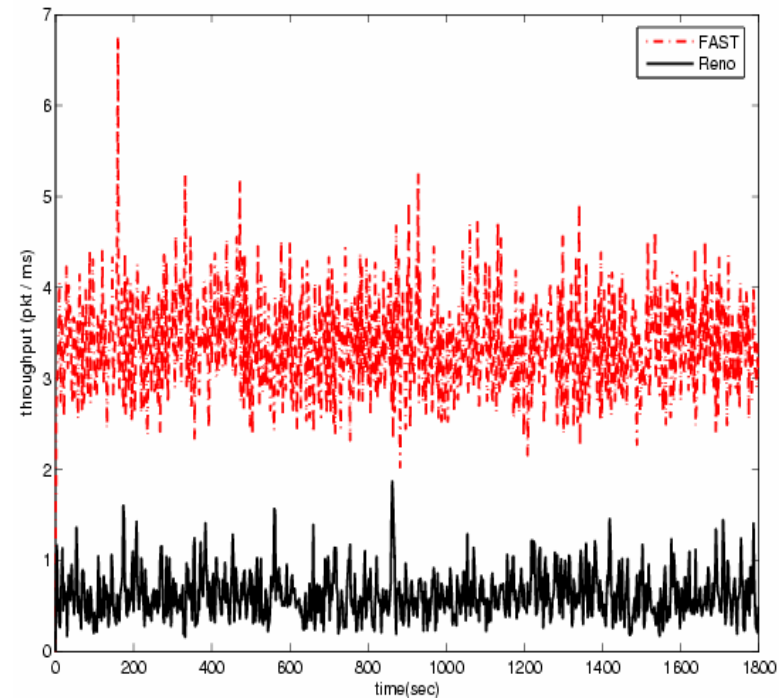


# The world is heterogeneous...

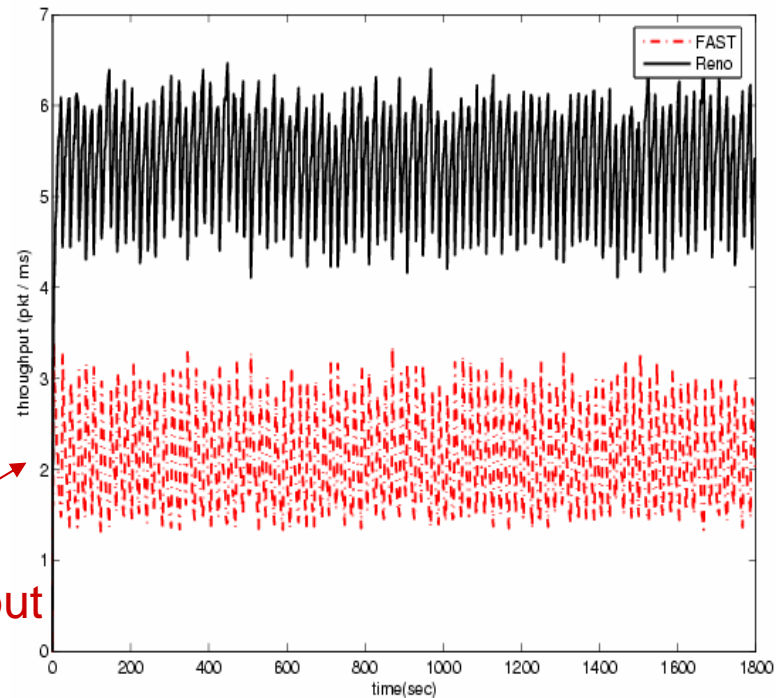
- Linux 2.6.13 allows users to choose congestion control algorithms
- Many protocol proposals
  - Loss-based: Reno and a large number of variants
  - Delay-based: CARD (1989), DUAL (1992), Vegas (1995), FAST (2004), ...
  - ECN: RED (1993), REM (2001), PI (2002), AVQ (2003), ...
  - Explicit feedback: MaxNet (2002), XCP (2002), RCP (2005), ...



# Throughputs depend on AQM



buffer size = 80 pkts



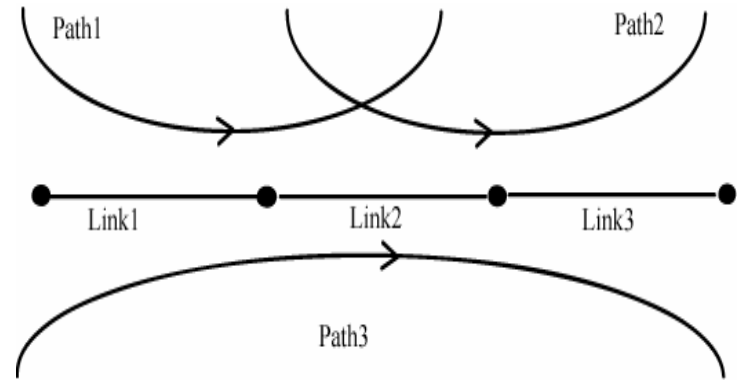
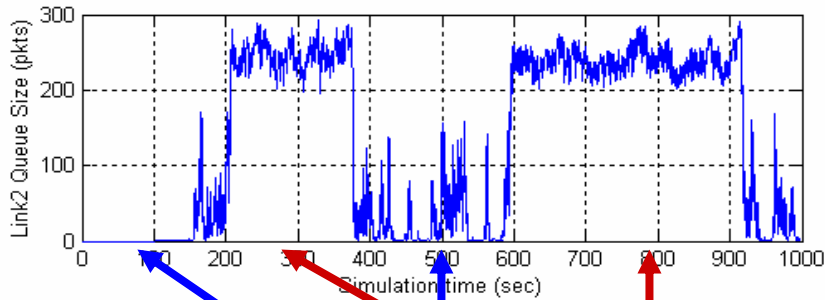
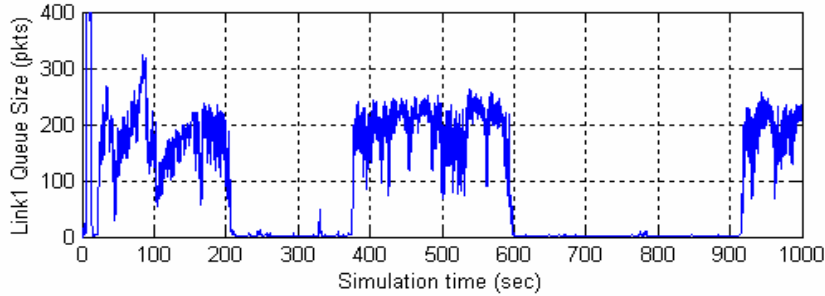
buffer size = 400 pkts

FAST throughput

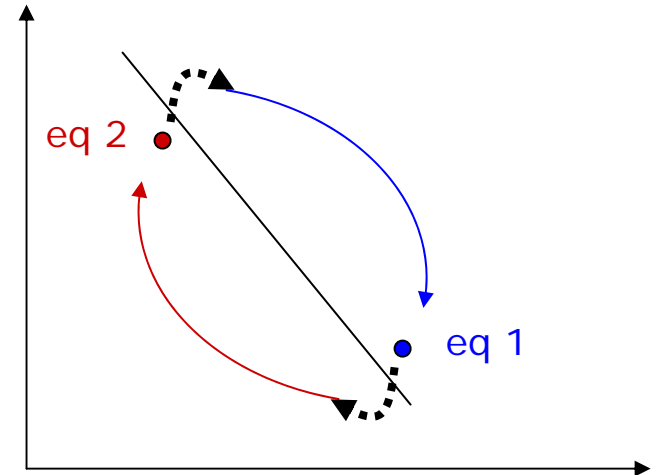
- FAST and Reno share a single bottleneck router
- NS2 simulation
- Router: DropTail with variable buffer size
- With 10% heavy-tailed noise traffic



# Multiple equilibria: throughput depends on arrival



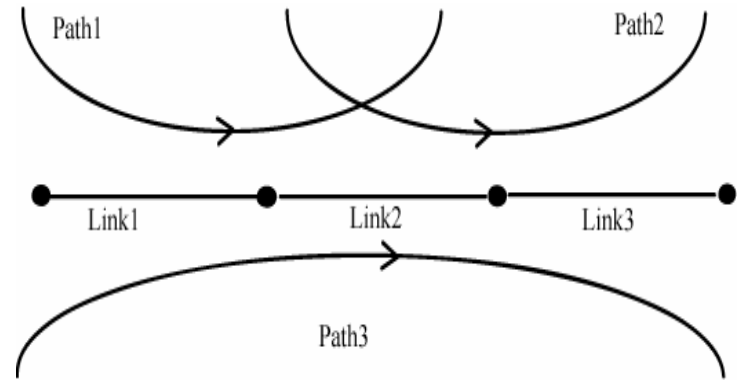
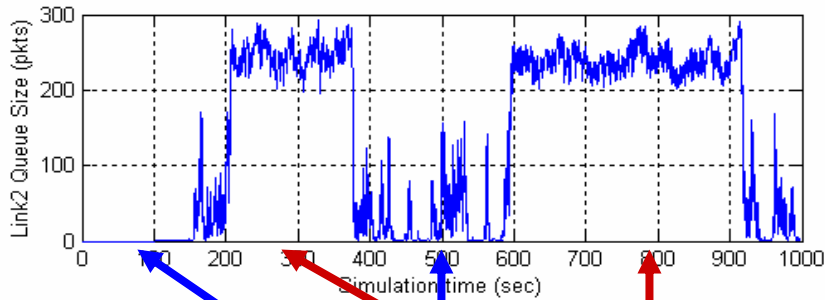
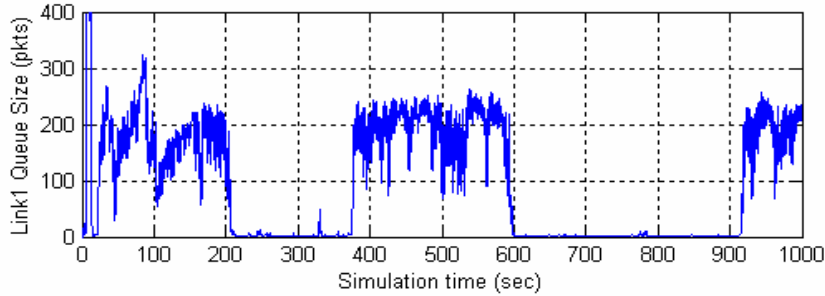
Dummysnet experiment



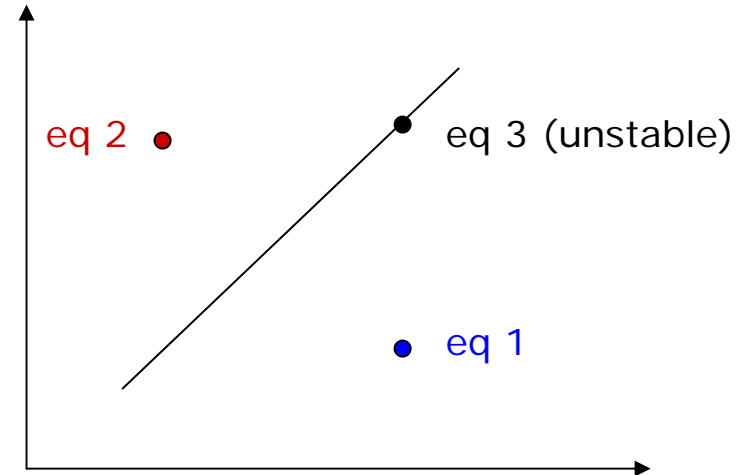
	eq 1	eq 2
Path 1	52M	13M
path 2	61M	13M
path 3	27M	93M



# Multiple equilibria: throughput depends on arrival



Dummysnet experiment



	eq 1	eq 2
Path 1	52M	13M
path 2	61M	13M
path 3	27M	93M



# Some implications

	<b>homogeneous</b>	<b>heterogeneous</b>
<b>equilibrium</b>	unique	non-unique
<b>bandwidth allocation on AQM</b>	independent	dependent
<b>bandwidth allocation on arrival</b>	independent	dependent



□ Duality model:

$$\max_{x \geq 0} \sum U_i(x_i) \quad \text{s.t.} \quad Rx \leq c \quad x_i^* = F_i \left( \sum_l R_{li} p_l^*, x_i^* \right)$$

□ Why can't use  $F_i$ 's of FAST and Reno in duality model?

They use **different** prices!

$$F_i = x_i + \frac{\gamma_i}{T_i} \left( \alpha_i - x_i \sum_l R_{li} p_l \right) \longleftarrow \text{delay for FAST}$$

$$F_i = \frac{1}{T_i^2} - \frac{x_i^2}{2} \sum_l R_{li} p_l \longleftarrow \text{loss for Reno}$$



□ Duality model:

$$\max_{x \geq 0} \sum U_i(x_i) \quad \text{s.t.} \quad Rx \leq c \quad x_i^* = F_i \left( \sum_l R_{li} p_l^*, x_i^* \right)$$

□ Why can't use  $F_i$ 's of FAST and Reno in duality model?

They use different prices!

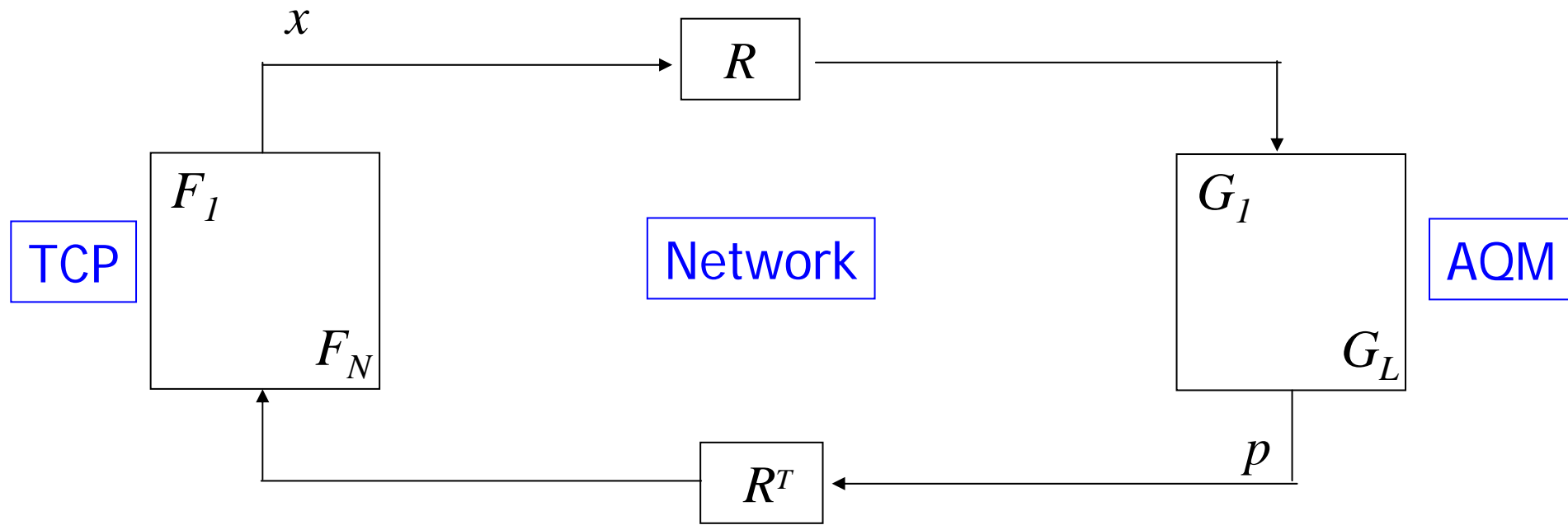
$$F_i = x_i + \frac{\gamma_i}{T_i} \left( \alpha_i - x_i \sum_l R_{li} p_l \right) \quad \dot{p}_l = \frac{1}{c_l} \left( \sum_i R_{li} x_i(t) - c_l \right)$$

$$F_i = \frac{1}{T_i^2} - \frac{x_i^2}{2} \sum_l R_{li} p_l \quad \dot{p}_l = g_l \left( p_l(t), \sum_i R_{li} x_i(t) \right)$$





# Homogeneous protocol

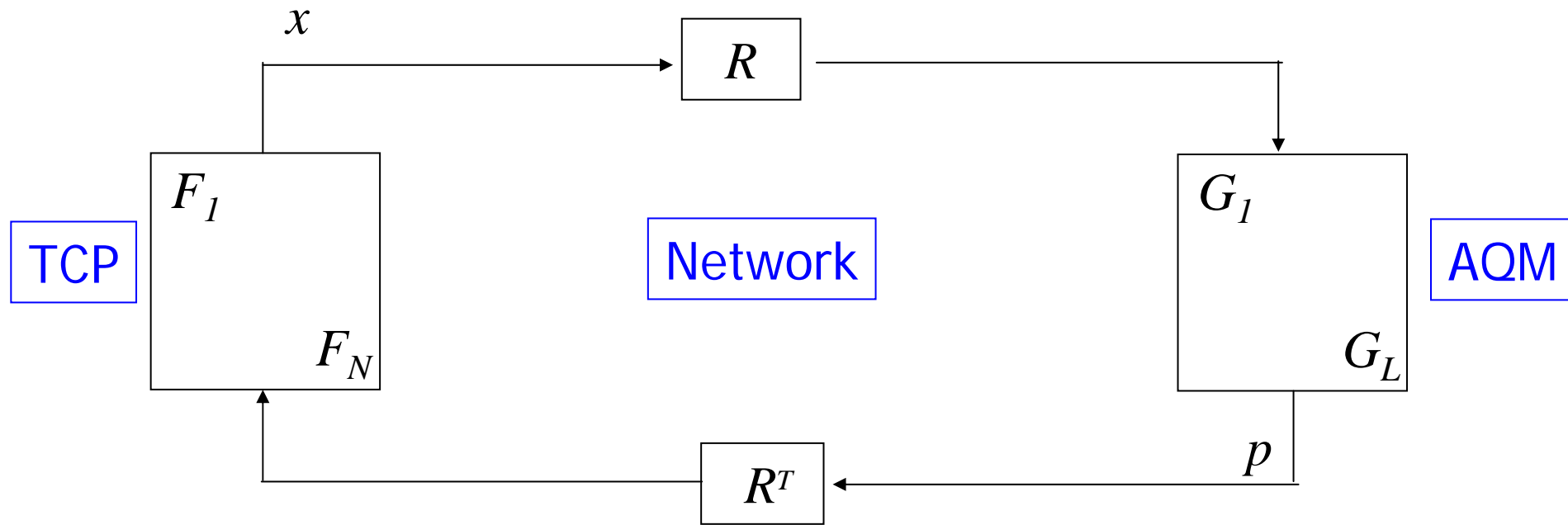


$$x_i(t+1) = F_i\left(\sum_l R_{li} p_l(t), x_i(t)\right)$$

same price  
for all sources



# Heterogeneous protocol



$$x_i(t+1) = F_i \left( \sum_l R_{li} p_l(t), x_i(t) \right)$$

$$x_i^j(t+1) = F_i^j \left( \sum_l R_{li} m_l^j(p_l(t)), x_i^j(t) \right)$$

heterogeneous  
prices for  
type  $j$  sources



# Heterogeneous protocols

□ Equilibrium:  $p$  that satisfies

$$x_i^j(p) = f_i^j \left( \sum_l R_{li} m_l^j(p_l) \right)$$

$$y_l(p) := \sum_{i,j} R_{li}^j x_i^j(p) \begin{cases} \leq c_l \\ = c_l \end{cases} \quad \text{if } p_l > 0$$

Duality model no longer applies !

■  $p_l$  can no longer serve as Lagrange multiplier



# Heterogeneous protocols

□ Equilibrium:  $p$  that satisfies

$$x_i^j(p) = f_i^j \left( \sum_l R_{li} m_l^j(p_l) \right)$$

$$y_l(p) := \sum_{i,j} R_{li}^j x_i^j(p) \begin{cases} \leq c_l \\ = c_l \end{cases} \quad \text{if } p_l > 0$$

Need to re-examine all issues

- Equilibrium: exists? unique? efficient? fair?
- Dynamics: stable? limit cycle? chaotic?
- Practical networks: typical behavior? design guidelines?



# Heterogeneous protocols

□ Equilibrium:  $p$  that satisfies

$$x_i^j(p) = f_i^j \left( \sum_l R_{li} m_l^j(p_l) \right)$$

$$y_l(p) := \sum_{i,j} R_{li}^j x_i^j(p) \begin{cases} \leq c_l \\ = c_l \end{cases} \quad \text{if } p_l > 0$$

□ Dynamic: dual algorithm

$$x_i^j(p(t)) = f_i^j \left( \sum_l R_{li} m_l^j(p_l(t)) \right)$$

$$\dot{p}_l = \gamma_l (y_l(p(t)) - c_l)$$



# Existence

## Theorem

Equilibrium  $p$  exists, despite lack of underlying utility maximization

- Generally non-unique
  - There are networks with unique bottleneck set but infinitely many equilibria
  - There are networks with multiple bottleneck set each with a unique (but distinct) equilibrium



# Regular networks

## Definition

A *regular network* is a tuple  $(R, c, m, U)$  for which all equilibria  $p$  are locally unique, i.e.,

$$\det \mathbf{J}(p) := \det \frac{\partial y}{\partial p}(p) \neq 0$$

## Theorem

- Almost all networks are regular
- A regular network has finitely many and odd number of equilibria (e.g. 1)



# Global uniqueness

$$\dot{m}_l^j \in [a_l, 2^{1/L} a_l] \text{ for any } a_l > 0$$

$$\dot{m}_l^j \in [a^j, 2^{1/L} a^j] \text{ for any } a^j > 0$$

## Theorem

- If *price heterogeneity* is **small**, then equilibrium is globally unique

## Corollary

- If price mapping functions  $m_l^j$  are linear and link-independent, then equilibrium is globally unique

e.g. a network of RED routers with slope inversely proportional to link capacity almost always has globally unique equilibrium





# Global uniqueness

$$\dot{m}_l^j \in [a_l, 2^{1/L} a_l] \text{ for any } a_l > 0$$

$$\dot{m}_l^j \in [a^j, 2^{1/L} a^j] \text{ for any } a^j > 0$$

## Theorem

- If *price heterogeneity* is **small**, then equilibrium is globally unique

## Remarks:

- Condition independent of  $U, R, c$
- Depends on  $m$  and size  $L$  of network
- "Tight" from Index Theorem



# Local stability: 'uniqueness' $\rightarrow$ stability

$$\dot{m}_l^j \in [a_l, 2^{1/L} a_l] \text{ for any } a_l > 0$$
$$\dot{m}_l^j \in [a^j, 2^{1/L} a^j] \text{ for any } a^j > 0$$

## Theorem

- If *price heterogeneity* is **small**, then the unique equilibrium  $p$  is locally stable

Linearized dual algorithm:  $\delta \dot{p} = \gamma \mathbf{J}(p^*) \delta p(t)$

Equilibrium  $p$  is *locally stable* if

$$\text{Re } \lambda(\mathbf{J}(p)) < 0$$



# Local stability: 'converse'

## Theorem

- If all equilibria  $p$  are locally stable, then it is globally unique

## Proof idea:

- For all equilibrium  $p$ :  $I(p) = (-1)^L$
- Index theorem:

$$\sum_{\text{eq } p} I(p) = (-1)^L$$

# Future directions

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- Dynamics of TCP
  - Global stability of networks in the presence of delay
  - Rate of convergence
  - Characterize/bound instability
- Heterogeneous congestion control protocols
  - Local and global stability in the presence of delay
  - Stability with slow-timescale control
  - Dynamic behavior in the presence of multiple equilibria
- Non-convex utility functions
  - Estimating duality gap and asymptotic behavior
  - Instability of dual algorithm as network size tends to infinity

# Future directions

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- TCP/IP interactions
  - Connection between duality gap and NP hardness
  - Connection between duality gap and multi-path gain
- Routing/economics interactions
  - Inter-domain routing: interplay between routing protocols and economics
  - Optimizations and games over routes, traffic demands, and pricing