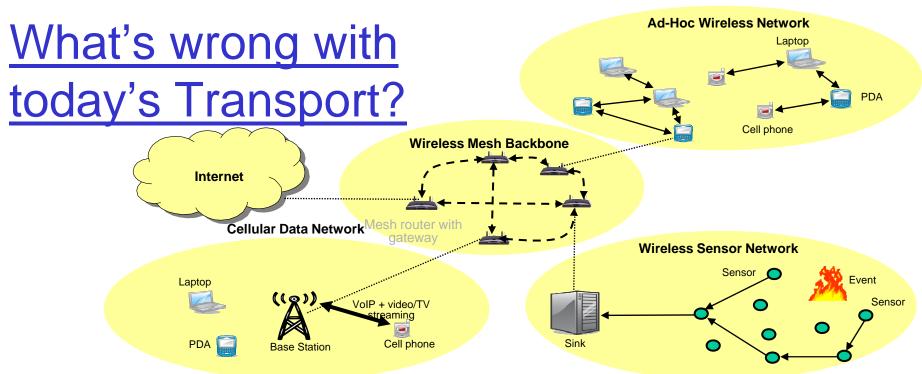
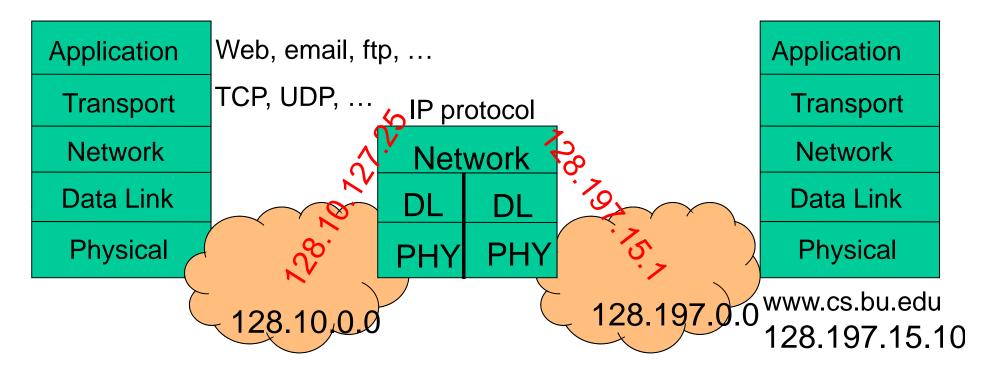
Revisiting a Soft-State Approach to Managing Reliable Transport Connections

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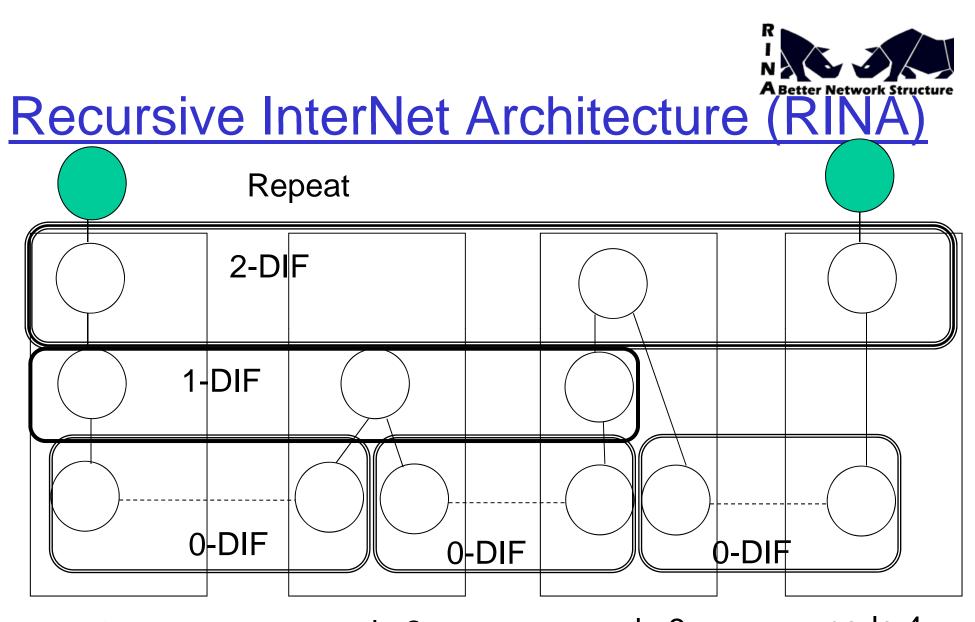


- The new brave world
 - Larger scale, more diverse technologies
 - New services: content-driven, context-aware, mobile, socially-driven, secure, profitable, ...
- Custom point-solutions: No or little "science"
- Lots of problems: bad performance, hard to manage, hard to adopt, ...

Internet's view: one big, flat, open net



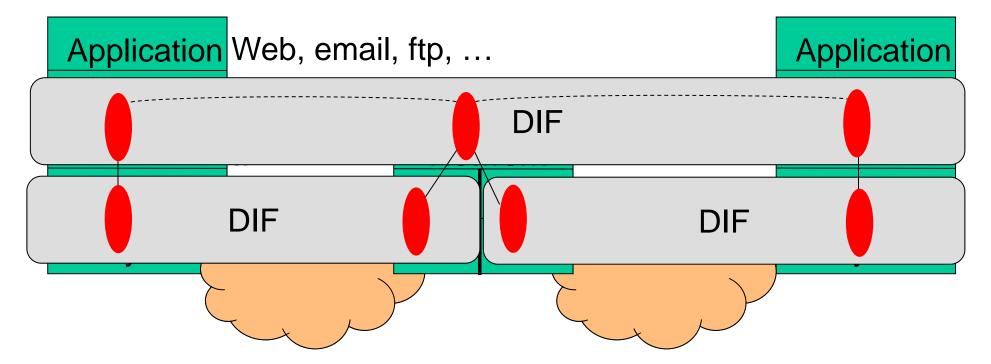
- There's no building block
- The "hour-glass" model imposed a least common denominator



node 1node 2node 3node 4DIF = Distributed IPC Facility (locus of shared state=scope)Policies are tailored to scope of DIF

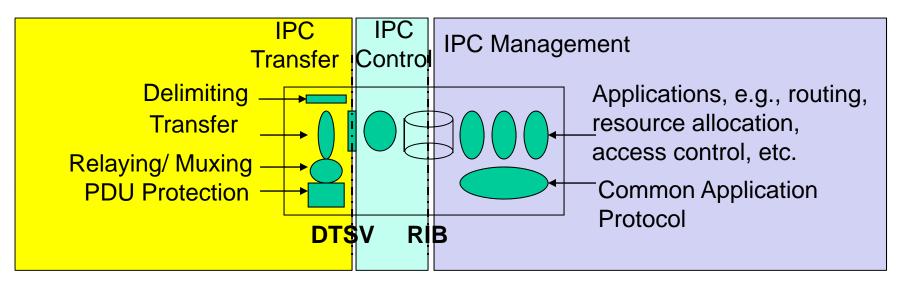
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RINA allows scoping of services



- The DIF is the building block and can be composed
- Good we split TCP, but we split TCP in the wrong direction!
- E2E (end-to-end principle) is not relevant
 - Each DIF layer provides (transport) service / QoS over its scope

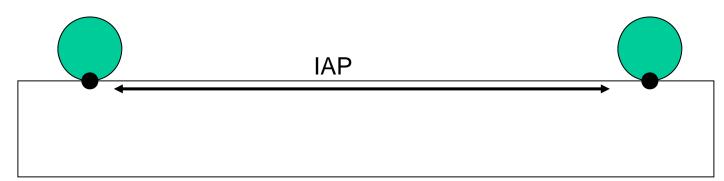
What Goes into a DIF?



Processing at 3 timescales, decoupled by either a Data Transfer State Vector or a Resource Information Base

- IPC Transfer actually moves the data
- IPC Control (optional) for error, flow control, etc.
- IPC Management for routing, resource allocation, locating applications, access control, monitoring lower layer, etc.

Only one Data Transfer Protocol



- RINA decouples port allocation and access control from data transfer
- Allocating conn ID (ports) is done by management, IPC Access Protocol (IAP), in a hard-state (HS) fashion
- Once allocated, Data Transfer can start, ala Delta-t [Watson'81]
 - Flows without data transfer control are UDP-like. Flows without reliability requirement do not ACK. Different policies support different requirements
- Delta-t is a soft-state (SS) protocol
- If there is a long idle period, conn state is discarded, but ports remain

Why not TCP?

□ Hard-state must be explicitly discarded

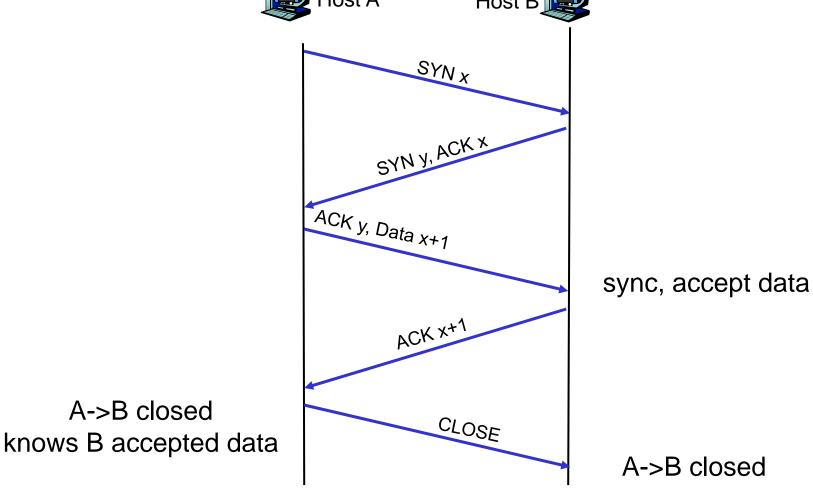
- But we don't need it to be [Watson '81]
- □ Watson proves that if 3 timers are bounded:
 - Maximum Packet Lifetime (MPL)
 - Maximum time for retries (G)
 - Maximum time before ACK (UAT)
 - That no explicit state synchronization, i.e., hardstate, is necessary
 - SYNs, FINs are unnecessary
- □ In fact, TCP uses all these timers and more

□ TCP is really hybrid HS+SS

This paper ...

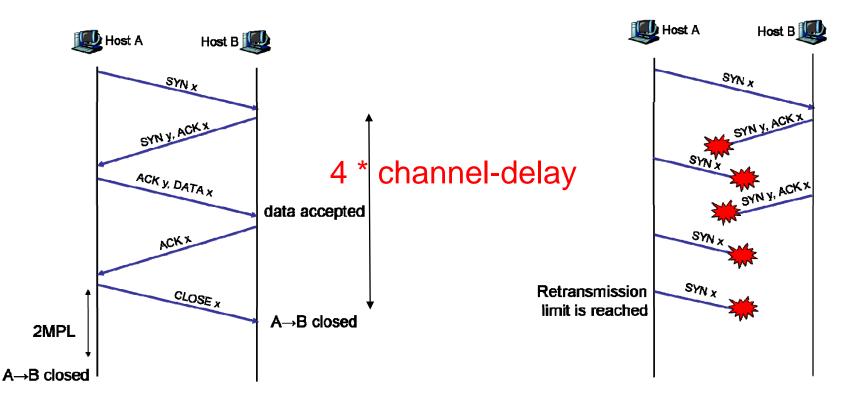
- Revisit connection management for reliability, i.e. to ensure no data loss and no data duplication
- Previous studies focused on correctness
- Here we focus on performance and robustness
- We consider worst-case single-message conversation
 - No flow / congestion control
- □ We compare four approaches:
 - Two-packet exchange (DATA + ACK)
 - Three-packet (... + CLOSE)
 - Five-packet (ala TCP)
 - O Delta-t

Reliable One-Message Delivery using five-packet handshaking Host A Host B

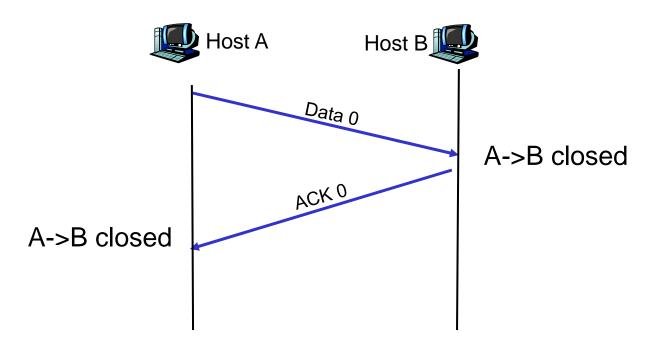


Five-Packet Protocol (ala TCP)

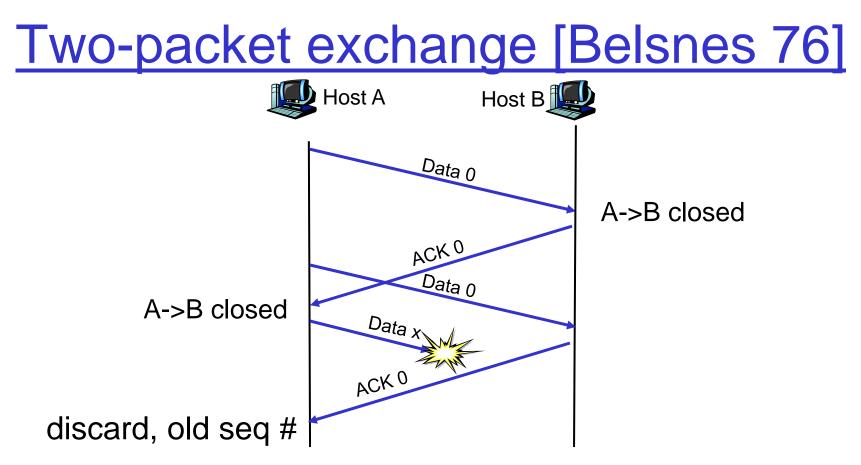
- Explicit handshaking: SYN and SYN+ACK messages
- For single-message communication, TCP uses fivepacket protocol + timers (HS+SS)
- □ Vulnerability: Aborted connections ⊗



Two-packet exchange [Belsnes 76]



- Premature timeout results in duplicate
- Duplicate ACK may ACK a lost "new Data 0"



•Solution to lost data:

use a new seq # that does NOT wrap around for at least 2 * MPL (Max Packet Lifetime)

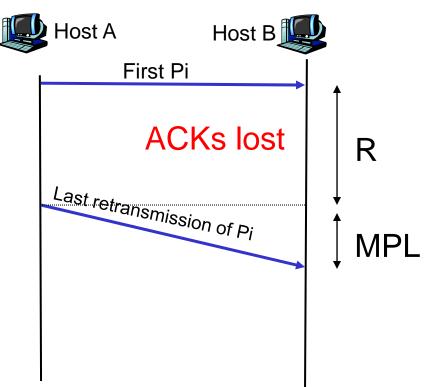
 Duplicates still possible if ACK is lost, even with RTO > 2 * MPL

Delta-t [Watson 78]

Two-packet exchange suffices if we can leave it to applications to detect duplicates

Delta-t solves the duplicate problem of twopacket using appropriate timers for keeping conn. state

Delta-t: Conn. Open [Watson 78]

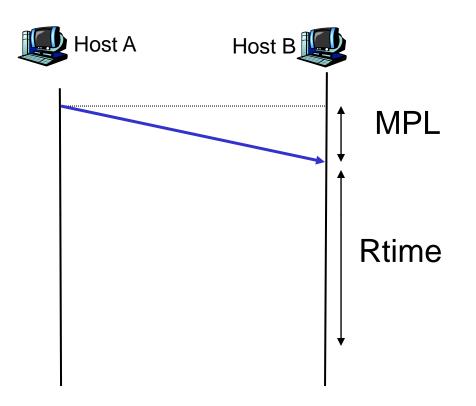


 Delta-t receiver does not delete state for at least Rtime = R+MPL

enough for duplicates to die out

- R = max time for retransmission attempts
- Rtime reset at every reception of new in-seq packet

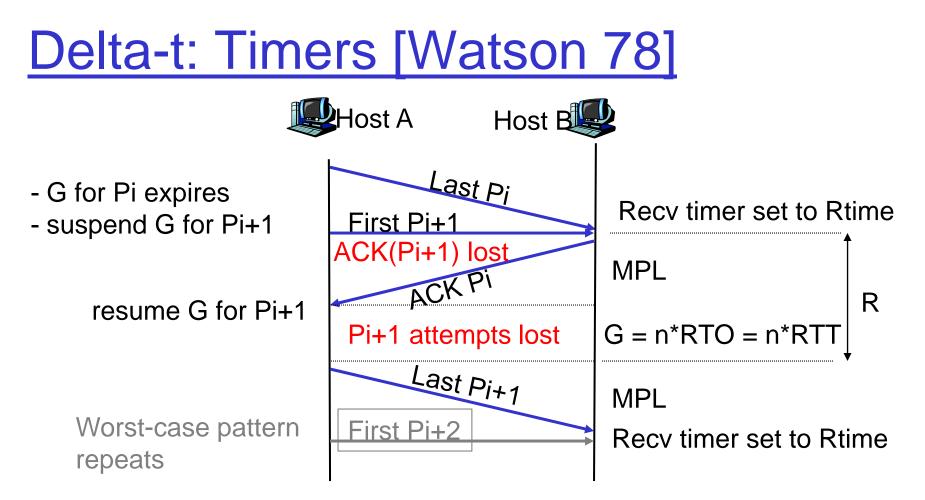
Delta-t: Conn. Close [Watson 78]



• Delta-t sender does not delete state for at least Stime = Rtime+MPL

enough to ensure sender does not delete state before receiver

• Stime reset at every transmission



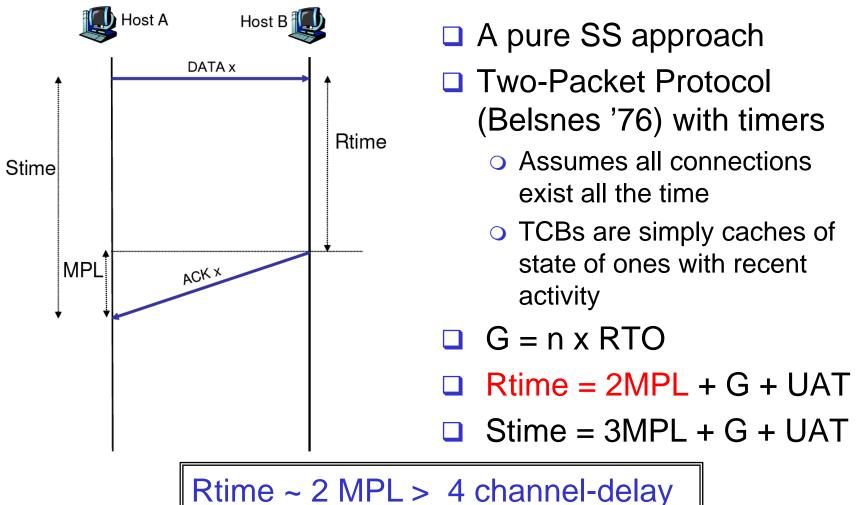
- Rtime >= $R + MPL = (MPL + G) + MPL \sim 2MPL$, if MPL>>G
- Stime >= Rtime+MPL ~ 3MPL

* Figure ignores UAT

Moral of the Story

- We need timers anyway
- □ We need to know something about MPL anyway
- We may need to reliably send a single message, or a stream of messages
- □ We should just use Delta-t anyway ☺
- No need to worry about init seq # since conn. ID / state is not released (re-used) until all its packets have died out

Delta-t Protocol (Watson 81)

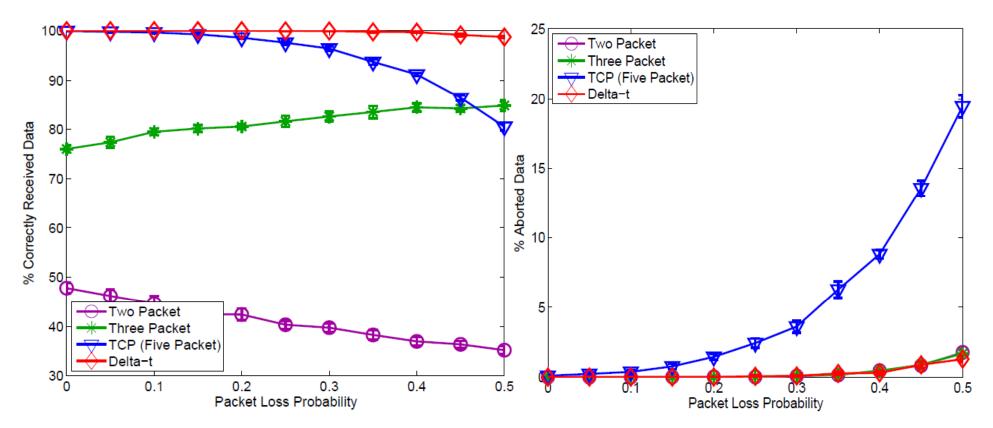


□ Memory requirement is not a concern

only few MB needed at Delta-t receiver (server) in a typical setting
We should revisit MPL: should be seconds rather than minutes!

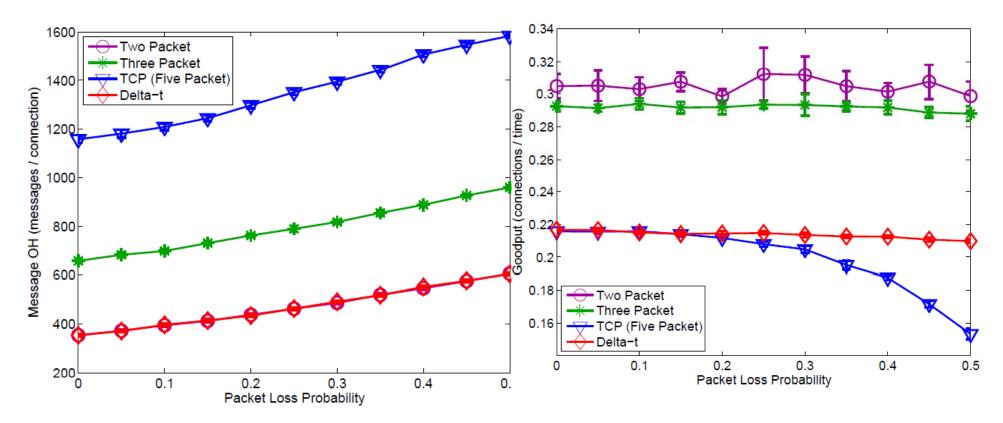
Simulation Results: Correctness

Two-state channel-delay model, random initial sequence numbers



□ SS (Delta-t) is more robust to bad net conditions

Simulation Results: Performance



 SS (Delta-t) has higher goodput and lower message overhead than HS+SS (TCP)

Conclusion

- SS is more robust to high packet losses and channel delay variations
 - No explicit handshaking messages for opening and closing connections
- SS can more easily establish its connections while delivering data reliably
- In our RINA architecture, port allocation and access control is decoupled from data transfer
 - Data transfer is done in an SS fashion
 - Port allocation and access control is HS
 - More @ http://csr.bu.edu/rina